Chapter 7 Rnet Communication

7.1 Overview

The major characteristics of Rnet network are the cost saving of installation/maintenance, diversification of system configuration, easy maintenance and repair, easy system change. This network supports the electrical network (twisted pair cable) that is cost effective and easy to install for the diversification of configuration.

Rnet module can be used in common for GLOFA series and MASTER-K series and applied diversely according to the system application.

Туре	Rnet V1.0	Remarks
	G3L-RUEA	GM3/K1000S Rnet (electric)
Master (RMM)	G4L-RUEA	GM4/K300S Rnet (electric)
	G6L-RUEA	GM6/K200S Rnet (electric)
	G7L-RUEA	GM7/K80S Rnet (electric)

In Rnet version V1.0, GLOFA Rnet and MASTER-K Rnet module can be in common.

7.2 Communication Specification

Remote I/O	module a	transmission	specification	(master	standard))
				•		

Items		Specification	
	Transmission speed	1Mbps(Rnet module common)	
	Encoding method	Manchester Biphase-L	
	Transmission distance (per segment)	Max. 750m	
Electric	Transmission distance	Max. 750m * (6 repeaters + 1)	
	(when using the repeater)	= 5.25km	
Transmission wire		Twisted pair shield cable	
Max. no of station number		Master + slave = 64 stations (at least one master should be connected.)	
Max. protocol size		256 bytes	
Access type of Communication		Circulated Token Passing	
Communication method		Connection Oriented service Connectionless service	
Frame error check		CRC $16 = X^{15} + X^{14} + X^{13} + \dots + X^2 + X + 1$	

7.3 Communication Parameter Setting

7.3.1 Overview

The method to program in RNET communication module is supposed to enable to communicate with Smart I/O module through *High Speed Link* service as mentioned on Chapter 4 'Communication Programming'.

High Speed Link

The *High Speed Link* service through Rnet communication module is available to use all the existing function and carry out the communication by simple parameter setting. The parameter shall be set in GMWIN for GLOFA series and in KGLWIN for MASTER-K and from RNET version V1.0, min. communication period can be set every scan.

1) Setting available range of Rnet communication module

Clas	sification	Max. communi- cation point	Max. sending point	Max. block no.	Max. point per block
RNET	G3L-RUEA	3,840 words	1,920 words	64 (0-63)	60 words
Communi	G4L-RUEA	3,840 words	1,920 words	64 (0-63)	60 words
cation	G6L-RUEA	3,840 words	1,920 words	64 (0-63)	60 words
module	G7L-RUEA	3,840 words	1,920 words	64 (0-63)	60 words

max. High Speed Link point per communication model(Rnet master standard)

Communication setting when communicating with Smart I/O module

HS link block setting		Sending/	Addres	ss area	HS link
Sending	Receiving	Receiving period	GLOFA-GM	MASTER-K	information
32	32	20ms ~ 10s	%QW, %IW	P area	Ref.7.3.2

Remark

- 1) In case of Smart I/O, if 32 points are installed for one module, max. link point is available to use up to 2,016 words for 63 stations.
- 2) For further information, please refer to 'Chapter 4. Communication Programming'.

7.3.2 High Speed Link Communication Status Flag

1) High Speed Link information function

It is available to confirm the reliability of data sent/received to/from other station (remote station) through *High Speed Link* and the user can utilize the above information by combining with *High Speed Link* sending/receiving data as keyword type when writing the program in case of emergency or maintenance.

Classification	Run-link	Link-trouble LINK_ TROUBLE	Sending/ receiving status TRX_MODE	Action mode DEV_MODE	Error DEV_ERROR	High Speed Link status HS_STATE
Information	Overall	Overall	Individual	Individual	Individual	Individual
type	information	information	information	information	information	information
Keyword name (□=HS link no. 1,2,3,4)	_HSORLINK	_HSOLTRBL	_HS⊡TRX[n] (n=individual parameter no.0~63)	_HS□MOD[n] (n=individual parameter no. 0~63)	_HS⊡ERR[n] (n=individual parameter no. 0~63)	_HS⊡STATE[n] (n=individual parameter no. 0~63)
Data type	BIT	BIT	BIT-ARRAY	BIT-ARRAY	BIT-ARRAY	BIT-ARRAY
Monitoring	Available	Available	Available	Available	Available	Available
Program	Available	Available	Available	Available	Available	Available

High Speed Link Information

7.3.3 GMWIN High Speed Link Setting

1) GMWIN project and Link parameter

If you select the *High Speed Link* parameter from GMWIN project basic screen, the *High Speed Link* parameter basic screen will appear and you can select the corresponding item.



If selecting 'parameter'-'*High Speed Link* parameter' from project screen, the above menu will appear.

High Speed Link parameter	basic screen through GM7 master
ommunicaton Parameter	
Communication Method ——	
Station No. : 0	Y
Baud Rate : 19200	Data Bit : 8
Parity Bit : None	Stop Bit : 1
Communication Channel	
C RS232C Null Modern (or RS422/485
C RS232C Modem (Ded	icated Line) Init. Command :
C R6232C Dial Up Mode	m ATZ
	J
Protocol and Mode	
	Timeout in Master Mode : 500 ms
Dedicated	
C Master	Read Status of Slave PLC List
C Slave	
Modbus	
C Master	
C Slave	
User Defined	
C Master	List
C Slave	
Master	List
O Slave	
Ok	Cancel Help

In case of GM7 RNET, select [parameter]-[*High Speed Link* parameter] from project screen.

2) Setting function

The *High Speed Link* items 1~4 means max. installation number of communication module according to PLC CPU type. It is available to install max. 4 communication module for GLOFA GM1/GM2/GM3 CPU/GM4-CPUB, max. 2 for GLOFA GM4-CPUA/GM6 and max. 1 for GM7.

Classification	Available communication module	Max. installation number (note 1)
GLOFA-GM3	G3L-RUEA	4 EA
GLOFA-GM4-CPUA	G4L-RUEA	2 EA
GLOFA-GM4-CPUB	G4L-RUEA	4 EA
GLOFA-GM6	G6L-RUEA	2 EA
GLOFA-GM7	G7L-RUEA	1 EA

Communication module installation relation per CPU model

3) Link parameter setting

If you select the corresponding parameter from parameter setting basic screen, the *High Speed Link* parameter setting first screen will appear as shown in the following figure. If setting the parameter at first, the initial value will be indicated as shown on the figure below.

Parameter setting screen

High Speed Li	nk 1				<u>.</u>	×
Networ	rk Type:	GLOFA F	net			
Slot:	0	Self Statior	n No: O			
					Edit	
Entry List						
Num	Туре	Class	From Area	To Area	Size	
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15						
		Del	ete Cor	ру	Edit	
				Close	Help	

Parameter setting initial screen is composed of two items such as 'link setting' and 'Entry list' and the setting method per each item and its function is as follows.

(1) Link setting

Link setting is the item to set the basic items of communication module to perform the *High Speed Link*.

High Speed Link set screen

High Speed1Link Set	×
Network Type	ок
GLOFAFnet	Cancel
C GLOFA Miner	
	Help
C GLOFA Ednet Network	
C GLOFA Foner Cable	
C GLOFA Dret	
GLOFA Rnet	
Self-stat Num	

Network type : It sets the installed communication module type and Rnet shall be set.
Slot no. : It sets the position that the communication module to set is installed. (0 ~ 7 slot).
Station no. : Enters the setting self station no. into the station address switch of communication module front side. The self station no. of Rnet shall be set as '0' to use.

(2) G7L-RUEA link setting

Network Type	ок
O GLOFA Mnet	Cancel
C GLOFA Enet	Help
O GLOFA Ednet Network	
C GLOFA Ednet Cable	
O GLOFA Driet	
O GLOFA Priet	
O GLOFA FEnet	
O GLOFA FDEnet	
GLOFA Rnet	
Blot Num	

Network type : It sets GLOFA Rnet. Slot no. : Not-active Self station no. : The self station no. shall be set as '0' and used.

(3) Entry list setting

Entry list is the area to register the actual data sending/receiving information. For further information, please refer to Chapter 4. 'Communication Programming'.

Remark

GRL-DT4A among Smart I/O module has 'input' and 'output'. Thus, in case of using the Entry list, please be sure that two lists are required for one module. In this case, when sending/receiving, the station no. shall be set same but the block no. differently.

4) High Speed Link operation

After setting the High Speed Link parameter and executing 'make' from GMWIN compile menu, if you select 'parameter write' and start the High Speed Link service, the High Speed Link service by the parameter setting begins to run. The High Speed Link start order is as follows.

(1) Parameter write



Parameter download screen

After saving the *High Speed Link* parameter written by the user in the GMWIN project file and connecting with PLC through 'online connect' from GMWIN basic menu, select 'write' and download the *High Speed Link* parameter or 'parameter and program'.

(2) High Speed Link start

Link Enable setting	9	
Set Link Enable		×
H-SLink 1	Πн	-Slink 2
		O Enne 2
ОК	Cancel	Help

(3) G7L-RUEA High Speed Link start

GMWIN fo	or Windows 🛛 🔀
i	Communication is enabled
	ूर्ट्ट इन्छ

After parameter write, *High Speed Link* is executed after setting the 'Link enable'. Link enable setting is available only in the stop mode of PLC. And if the *High Speed Link* enable setting starts, it carries out the *High Speed Link* regardless of PLC action mode and 'parameter' and 'Link enable information' shall be battery backup in the PLC CPU and preserved if the power is cut off.

(4) High Speed Link information monitor

It is available to monitor the current *High Speed Link* status by using 'monitor' function after the GMWIN online connection. There are two kinds of methods to monitor : by selecting 'variable monitor' from monitor menu and by high speed parameter monitor.

Variable monitor

'Variable monitor' is the function to monitor the necessary items by using the GMWIN flag monitor function and the order to monitor is as follows.

- ① Select Variable monitor from online monitor items.
- ② Select **O flag** from 'register variable ' screen as shown on the figure.
- ③ Select the High Speed Link information flag you want to monitor directly one by one from Variable, Flag list screen and register. (As _HSxSTATE[n], _HSxERR[n], _HSxMOD[n],_HSxTRX[n] is ARRAY flag, the user enters the registration no. of parameter that he wants to monitor directly).

Remark

'x' shows the *High Speed Link* no. and it has the range1~4 for GM1/GM2/GM3/GM4-CPUB PLC, 1~2 for GM4-CPUA,GM6 PLC and only 1 is effective for GM7. [n] is the individual parameter no.(0~63).

If you register the variable from the menu and select 'close', the corresponding monitor screen will appear and the monitoring begins.

Register Variable			×
_ Kind			
C Configuration Global Varia	ble 🙃 Resource Glob	al Variahle	Close
			Re <u>q</u> ister
C Instance Variable	System Flag		Colort
			<u>Select</u>
			Help
Ex) %I>	0.0.0 or %QX0.1.0-%QX0.1.8		
Resource Resource0	. Instance	INSTO	7
⊻ariables,System Flags	Registered	I-Variables	
_H_BCK_ER Hot resta	t unable error 🔺		
HS1ERR Station st HS1LTRBL Abnorma	atus informatil information o		
HS1MOD Station m	ode informatic		
HS1RLINK HS RUN	LINK informat—		
_HS1STATE General (ommunicatior		
_HS1TRX Commun	ication status		
_HSZERR Station st			

High Speed Link information variable register screen

🔍 User Selection V	ariable Monitor		<u>-0×</u>
System Flag System Flag System Flag System Flag System Flag System Flag	_HS1ERR[0] _HS1LTRBL _HS1MOD[0] _HS1RLINK _HS1STATE[0] _HS1TRX[0]	0 0 1 1 1 1 1	
•			F

High Speed Link information monitor screen (variable registration)

The detailed contents for the corresponding flag is described in 'Communication module flag application' and it is available to carry out the RNET network status diagnosis by the corresponding flag monitor properly.

· High speed parameter monitor

This is the function to monitor the *High Speed Link* communication status from the menu as below. Select 'link parameter' item from monitor menu of GMWIN online connection.



Link parameter monitor shows the general information for RUN-LINK, LINK-TROUBLE on the top screen as below and the individual information such as mode (action mode), communication (sending/receiving status), error on the setting parameter items.

IS Lini	k Parameter1 Monitor						
Run_l	Link:1 Link_	Trouble:()					
No	Туре	Class	From Area To	Area	Size Mode	Trx	Error 🔺
8	Remote1.Send0	A(20ms)	%MW0 %Q	W0.0.0	1 1	1	0 _
1					0	0	0
2					0	0	0
3					0	0	0
4					0	0	0
5					0	0	0
6					0	0	0
7					0	0	0
8					0	0	0 🔹

High Speed Link parameter monitor screen (Example)

For the meaning of the value monitored on the above figure, please refer to 'Chapter 4.



- Remark
- 1) RUN-LINK monitoring In case that GRL-TR4A among Smart I/O is set in the parameter, RUN-LINK shall be indicated as '0'.

7.3.4 KGLWIN Link Setting

1) KGLWIN project and Link parameter

High Speed Link parameter selects link parameter from KGLWIN project screen and sets the corresponding item. The setting order and the function per item are as follows.

(1) KGLWIN project setting

The following shows parameter basic screen appeared when selecting 'parameter' window.

Farameter [New Project1]		
Basic Interrupt I/O Link1	Link2	
Latch Area L:	Timer Boundary 100 msec T: 000 - 191 10 msec T: 192 - 255 Watchdog Time: 20 * 10msec PLC Operation Mode Ø Blown Fuse Ø Operation Error Output during Debugging Remote Access Control	Computer communication Station Number : 0 Baud Rate : 19200 Master Slave Time Out : 5 x1 Read Slave PLC State Setting Slot of External Interru

KGLWIN parameter basic screen (in case of K200S)

(2) Link parameter basic setting

If you select 'Link 1' from KGLWIN parameter basic screen, the *High Speed Link* 1 parameter basic screen as shown below will appear.

署Para	ameter [Nev	v Project1]				
Basic	c Interru	ipt I/O	Link1 Link2			
Link:	Enable	Self Station No	o: 💽 💌 Base: 🕻) 💌 Slot: 🛛	▼ Type: Fnet	•
No	Station	Unit Type	Tx Device	Rx De	vice Size	Block No 🔺
0 1 2 3 4 5 6 7 8 9 10 11 2 3 4 5 6 7 8 9 10 11 2 3 4 5 6 7 8 9 10 11 2 3 4 5 6 7 8 9 10 11 2 3 4 5 6 7 8 9 10 11 11 2 3 4 5 6 7 8 9 10 11 11 11 12 13 14 5 10 10 11 11 11 11 11 11 11 11 11 11 11						

Link parameter basic screen

(3) K80S project and Link parameter basic setting

This is parameter basic screen to be appeared when selecting K80S parameter window.

#Paramete	r [New Projec	:t1]			
Basic	Interrupt	Comm.	PID(TUN) PID(CAL) Pulse Ou	ıt Analog	
Latch Are	Ea L: *** M: **** ec T: 144 ec T: 240 C: 192 D: 3500 S: 80	- **** - **** - 191 - 255 - 255 - 4500 - 99	Timer Boundary 100 msec T: 000 - 191 10 msec T: 192 - 255 Watchdog Time: 20 * 10msec PLC Operation Mode PLC Operation Error Operation Error Output during Debugging Remote Access Control	Input Setting Input Filter Time : 8 Pulse Catch Set (POC 0 1 2 2 4 5 6)0X) 3 7

KGLWIN parameter basic screen (in case of K80S)

If selecting 'communication' from KGLWIN parameter basic screen as shown on the above figure, the communication parameter setting screen will appear as below and if you select 'master' from the FIELDBUS menu on the right bottom side and press 'register list', the *High Speed Link* parameter basic screen will appear.

Communication parameter setting screen

₩Parameter [New Project1]	<u>×□</u> .
Basic Interrupt Comm. PID(TUN) PID(CAL) P	ulse Out Analog
Communication : Disable -	Protocol and Mode Timeout in Master Mode: 500 ms
Station Number : 0 Baud Rate : 19200 V Data Bit : 8 V Parity Bit : None V Stop Bit : 1 V	Dedicated C Master TRead Status of Slave PLC
Communication Channel	C Master Transmission Mode: ASCI
C RS232C Modem(Dedicated Line) Init Command : C RS232C Dial-up Modem	User Defined C Master Slave FIELDBUS Master C Slave List
a	

FIELDBU	IS							×
Kind	Rnet	💌 Sel	f-Station No 🛛	•				
- Entry No	List Station	Туре	From Area	To Area	Size	Block No	Period	
0123456789 101121345 1121545 1121545 112155 112155 112155 112155 112155 112155 1121555 1121555 11215555 112155555555								
			Delete.	Co	ру	Edit.		
			OK	C	ancel	Help)	

Link parameter basic screen

Link1 : This is one of *High Speed Link* type and max.4 communication modules can be installed for K1000S CPU, max. 2 for K300S/K200S and max.1 for K80S. The *High Speed Link* no. is not related to the installed slot no. and only one *High Speed Link* parameter is available to set for one communication module. The table below shows the installation available communication module per CPU model and max. installation amount.

Classification	Communication module	Max. installation amount	Remarks
K1000S	G3L-RUEA	4 EA	
K300S (below v2.2)	G4L-RUEA	2 EA	Each communication
K300S (more than v2.2)	G4L-RUEA	4 EA	module can be installed
K200S	G6L-RUEA	2 EA	by combining each other.
K80S	G7L-RUEA	1 EA	

Relation of communication module installation per CPU model

- Link : It sets whether or not to execute the link of communication module. (Enable, Prohibit)
- Self station no. : Self station no. should be set as '0' and used.
- Slot : This is the communication module installed slot no. and it is set by selecting one from '0'~'7'.

• Registration no. : This is the serial no. to indicate the registered order of the

individual parameter and it is set by '0' ~'63'. It is available to register up to total 63 and not related to the sending/ receiving order. But it is available to register max. 32 for sending and 32 for receiving respectively.

(4) Link parameter detail setting

If you doubleclick in the status that the *High Speed Link* registration no.1 is selected, the link parameter setting screen will appear as shown on the figure below.

Link parameter modification screen (in case of the HS link registration no.0)

Edit Link	×
Station No: Tx Device: M000 Rx Device: P000 Block No: 0 💌 Size: 1	OK Cancel
Module Type: Remote Out 💌 Period: 20 msec 💌	

Station no. : If sending/receiving the data of the setting item, it is required to set other station no. The following table shows the method to set the station no.

Station no. setting method

Communication type	Station no.	Range of station no.
Remote sending	Station no. of other station	4 00
Remote receiving	(remote)	1~63

Block No. : This is the parameter to send/receive lots of data of various areas from one station and distinguish the data of various blocks each other. If setting 32 stations for Smart I/O output module, the input should be set as 31 stations and if setting 32 stations for input. The output should be set as 31 stations because this supports up to 64 stations including master station. In this case, if setting more than 2 same block no. for the same station no., the network will be down. Thus it is not available to set more than 2 block for the same station. The max. number of connection station is 64 stations including the master station but if the sending/receiving is set for the one station at the same time, it is not available to set max.

- Communication type : It is set by remote sending and remote receiving.
 Remote sending : when sending the data of self station to remote station.
 Remote receiving : when receiving the data of remote station to self station.
- Sending/Receiving device : This means the area of sending/receiving. In case of remote sending that means the sending to remote station, set the sending area of self station for the sending device and the receiving area (P area) of remote station for the receiving device. As the remote receiving means the receiving from remote station, set the sending area (P area) of remote station for the receiving area of self station for the receiving device.

Communication type	Device	Setting available area	Remarks
	Sending	P,M,L,K,F,D,T,C all area	Sending area of self station
Remote sending	Receiving	P area	Receiving area of remote station
Remote receiving	Sending	P area	Sending area of remote station
_	Receiving	P,M,L,K,D,T,C area	Receiving area of self station

Sending/Receiving device setting area per communication type

- Size : This means the size of sending/receiving data and the unit is 1 word (16 points). It is available to set max. 60words but for Rnet, it is set as 2 words at the present time because max. points of the current Smart I/O is 2words (32 points).
- Communication period : High Speed Link is the service to carry out the sending/receiving by the parameter set by the user at the point that PLC program ends. Thus, when PLC program scan time is short within several ms, communication module begins to transmit the data according to every program scan which results in increasing the communication amount and reducing the effectiveness of overall communication system. Thus, to prevent this, the user can set the sending/receiving period from min.20ms (RNET version V1.0 : from every scan) to max. 10sec. The sending/receiving period means the sending period if the corresponding block is set as 'sending' and the period to check the data receiving of the corresponding block if it is set as 'receiving'.

(5) High Speed Link operation

After completing the *High Speed Link* parameter setting, if you click the 'verify' button from download menu and execute the parameter download, the *High Speed Link* service begins. In this case, the corresponding link of the link parameter basic

screen should be Enable status.

Parameter download scre	en	
Download to PLC (KGLW	IN => PLC)	×
I Parameter I Program From 0	To 7167	
ОК	Cancel	

2) High Speed Link information monitor

After KGLWIN online connection, it is available to monitor *High Speed Link* information by using monitoring window and 'information read' window. There are two kinds of method to monitor : one is by selecting the flag to monitor from flag monitor menu of monitoring window to monitor the individual information and overall information and another one is by selecting the *High Speed Link* parameter from online-information read menu to monitor overall information.

• Flag monitor

Flag monitor is the function to monitor by selecting the necessary flag from KGLWIN [project] \rightarrow [monitoring] using the flag monitor menu. First, if you select flag monitor button from monitoring window, the flag monitor screen as shown on the figure below will appear and if you press the registration button (\checkmark), the flag registration screen will appear. Select the *High Speed Link* information flag to monitor from the flag registration screen one by one and register it. If flag registration is completed, it begins to monitor in 'monitor' screen. If the monitoring does not work, please check the monitor start mode once again.

Monitor [New Project1]		_	미꼬
Bit Word Double Word Flag	Device	▼ Num 1 ▼	
No Device Alias	Curre _fsm7_RESET _FSM7_ST_NO	▲etting Value Comment	
	LISUERR [15-0] LISUERR [31-16] LISUERR [47-32] LISUERR [63-48] LISUERR [63-48] LISUMOD [15-0] LISUMOD [15-0] LISUMOD [47-32]	•	

Flag monitor screen and Flag registration screen

Flag monitor screen (the flag is registered.)

Bit Word Double Word Flag Device Num 1 Image: Non No Device Alias Current Value Setting Value Comr 0 _hsORLINK D4600.0 1 1 _hsOLTRBL D4600.1 0 2 _HSOERR[15-0] D4613 00000/h0000/ 3 _HS1MOD[15-0] D4625 000000/h0000/	🕮 Mo	nitor [New Projec	t1]				<u> </u>
No Device Alias Current Value Setting Value Comr 0 _hsORLINK D4600.0 1 1 _hsOLTRBL D4600.1 0 2 _HSOERR[15-0] D4613 00000/h0000/ 3 _HS1MOD[15-0] D4625 00000/h0000/	Bit	Word Double	Word Flag [Device	•	Num 1	~
	No 0 1 2 3	Device _hsORLINK _hsOLTRBL _HSOERR[15-0] _HS1MOD[15-0]	Alias D4600.0 D4600.1 D4613 D4625	Current Value 1 0 00000/h0000/ 00000/h0000/	Sett	ing Value	

• Reading information in High Speed Link parameter monitor

If you select the *High Speed Link* parameter from the menu 'online-information read', you can see the detailed information for the *High Speed Link* parameter as shown on the above figure.

HS	Link Inform	ation							×
	OSIot/Rnet/Station No:00								
		-					(-	
	No 0	R02,S00	Period 20ms	IxArea M000	<u>HxArea</u> P000	Length	Mode O	Irx	Erro
	1	R03.S01	20ms	M000	P000	1	Ō		
	•								F
					ок				

High Speed Link parameter monitor

R02.R03 from the type item means Remote station (Smart I/0) 2 and 3 and SOO,S01 means the block no., and this is the parameter to transmit the data of self station (M000) to Remote (Smart I/O) station 2 (P000) through block no.'0'. R03 is also the parameter to transmit the data of self station (M000) to Remote (Smart I/O) station 3 (P000) through

block no.1.

· Link information monitor from information Read

If you select the menu 'online'-'information read'-'link information', it is available to monitor the link status of the communication module installed per slot easily.

Link Informatio	in		×
Slot No	Network Type	Station No	
0	GLOFA Rnet	00	
· · ·			
	OK	Network Information	

If you select the module to monitor and click the verify button, you can see the connection status of all RNET network connected to the corresponding module. **(except K80S)**

Link Informatio	n								<u></u>
Slot No	Networ	k Type	Stat	ion No					
		Aneo							
Network Infor	mation								×
Station	No	PLC Type	e	Mode	Error	Connection	Slot	No	
00		K200S		XXXX	-		0		
		SRU		XXXX	·		0		
				OK					

3) Flag

L area list when using the data link module (in case that installed in Slot no.0)

x : slot no., n : station no. of other station						
Keyword		Address no.	Description			
_NETx_LI V[n]	L0001~L003F	L0001 ~ L000F (1~15 stations) L0010 ~ L001F (16~31 stations) L0020 ~ L002F (32~47 stations) L0030 ~ L003F (48~63 stations) L0050 ~ L005F (16~31 stations) L0060 ~ L006F (32~47 stations) L0070 ~ L007F (48~63 stations)	This is the flag to inform that the power of other station is normal and the data is sending/receiving normally with other station through communication cable as the Alive information of other station. (Reading only)			

High Speed Link detail flag		x : K1000S=9,	K300S/K200S=4 m : HS link no.	
Keyword	Туре	Bit position	Items	Description
_HSmRLINK	Bit	Dx600.0	High Speed Link RUN_LINK information	 This indicates that all station are acting normally according to the parameter set in the high speed line and will be 'ON' under the following conditions. 1. When all station set in the parameter is RUN mode and there is no error, 2. When all data block set in the parameter is communicating normally, 3. When the parameter set in the parameter of each station itself is communicating normally, Once 'ON', RUN-LINK maintains the 'ON' unless stopped by Disable.
_HSmLTRBL	Bit	Dx600.1	Abnormal information of <i>High</i> Speed Link (LINK_TROUBLE)	 In the status that _HSmRLINK is ON, if the communication status of the station set in the parameter and the data block is as follows, this flag shall be ON. 1. When the station set in the parameter is not RUN mode, 2. When there is an error in the station set in the parameter, 3. When the communication status of data block set in the parameter is not smooth, LINK-TROUBLE shall be ON if the above 1,2,3 condition occurs, and if the condition returned to the normal condition, it shall be OFF.
_HSmSTATE[k] (k=0~63)	Bit Array	Dx601.0 ~ Dx604.15	General communication status information of k data block set in the <i>High Speed Link</i> parameter	This indicates the general status of communication information for each data block of the setting parameter. _HSmSTATE[k] = _HSmMOD[k] & _HSmTRX[k] & _HSmERR[k]

Keyword	Туре	Bit position	Items	Description
_HSmMOD[k] (k=0~63)	Bit Array	Dx605.0 ~ Dx608.15	Mode information (RUN = 1, others = 0)	Indicates the action mode of the station set in k data block of parameter.
_HSmTRX[k] (k=0~63)	Bit Array	Dx609.0 ~ Dx612.15	Status information (normal=1, abnormal=0)	Indicates whether the communication status of k data block of the parameter is communicating smoothly as set in the parameter.
_HSmERR[k] (k=0~63)	Bit Array	Dx613.0 ~ Dx616.15	The status information of the station set in k data block from the <i>High Speed Link</i> parameter. (normal=1, abnormal=0)	Indicates if the error occurs in the station set in k data block of the parameter.

High Speed Link detail flag when m=1~3

<u> </u>								
HS link type	D area address no.	Remarks						
High Speed Link2 (m=1)	Dx620 ~ Dx633	Comparing with m=0, D area address no. is as follows when m=3.						
High Speed Link3 (m=2)	Dx640 ~ Dx653	Calculation formula : when m=1~3, D area address no. address no. +						
High Speed Link4 (m=3)	Dx660 ~ Dx673	$20 \times m$						

7.4 Program Example

7.4.1 GLOFA-GM Series

Program Example 1 :

In GM3 base, the communication module (G3L-RUEA) is installed for slot 0, output 32 points for slot 1, and input 32 points for slot 2, respectively. This is the example to send GM3 %IW0.2.0 data to station 1 and output the data of station 2 to GM3 %QW0.1.0.



To perform the program example, first make the I/O configuration table as shown on the table below and write the *High Speed Link* parameter in the corresponding CPU module, respectively.

I/O configuration and Sending/receiving flow

Sending/receiving structure	Area to read	Storage area	Block no.	Size
Sending from GM3→station 1	%IW0.2.0	%QW0.0.0	0	1
Receiving from GM3←station 2	%IW0.0.0	%QW0.1.0	1	1

Working order

- 1) Station number allocation and communication cable connection
- 2) The user program writing (per each station)
- 3) Make the data sending/receiving map same type of the above table
- 4) Parameter setting in GMWIN High Speed Link parameter setting item
- 5) Execute 'compile' and 'make' from compile menu
- 6) Execute program and parameter write from online menu.
- 7) Select 'Link Enable set' from online menu and set the *High Speed Link* Enable that corresponds to the setting no.
- 8) Change the mode to RUN from online menu.
- 9) Start 'monitor' from online menu and check if RUN-LINK is ON without error in the *High Speed Link* monitor.
- 10) If the error occurs, repeat the above from 1).

High Sp	eed1Link	Otem Edit		×
Station Ty C Local	/pe	Station No	Mode Send Receive	Block No
- Area	C %MVV	⊙ %IW	© %QW 0.2.0	Send Period A(20ms)
То	C %MVV	O %IW	⊙%QW 0.0.0	Size
			OK Cancel	Help

Sending parameter setting from GM3 station 0 to station 1

Receiving parameter setting by GM3 station 0 from station 2

High Sp	eed1Link	1tem Edit		×
Station Type C Local C Remote		Station No	Mode Block No C Send 2 C Receive	
Area]	Send Period	_
From	C %MVV	⊙ %IW	C %QW 0.0.0	·
То	C %MVV	© %I₩	© %QW 0.1.0 Size	
			OK Cancel Help	

Remark

1) Do not register the same station no. more than 2 or the same block no. more than 2.

7.4.2 MASTER-K Series

Program Example 1

Here describes the *High Speed Link* parameter setting method to perform the data communication in RNET master system below with the I/O structure same as shown on the table below.

Network A (Rnet)



I/O configuration and Sending/receiving flow

:	Sending/receiving structure	Sending area	Receiving area	
K200S (station 0)		P0003	-	
	Sending :> GRL-IR2A(station 1)	-	P000	
		P0000	-	
	Receiving :< GRL-D24A(station 2)	-	P0004	

From the example, K200S CPU sends the input value of input module (P3) installed in self station slot 2 by 1 word and outputs the data received from other station to P4 output module. The *High Speed Link* parameter configuration and program for data exchange on the above is described in the figure below. The program can be used in common and sets only link parameter respectively. (it is available to use the same program and parameter in the K1000S/K300S RNET communication.)

1) The user program writing

📊 Progran	n [New Proj	iect1]				_ 🗆 🗵
	+ +/+	। <> == ÷	* • • • • •	. 🧠 💽 📰 📰 🖸 V 🗤 🗠	:	
o	—] в	D4600	00000]-		0000M	-
6	—] в	D4600	00001		<u>жооо1</u>	_
12					END	
•						

The above figure is the program to set M0000 area when RUN-LINK is ON and M0001 area when LINK-TROUBLE flag is ON.

(B) High Speed Link parameter setting

To make Station 0,1,2 to change the data as specified on the table in the master configuration system, the user should write the user program first and then prepare the data sending/receiving map as shown on the table. And to send/receive the data as shown on the table, it is required to write the High Speed Link parameter and download it in PLC and the High Speed Link start shall be carried out according to the following order.

- 1) Station number allocation and communication cable connection
- 2) The user program writing (per each station)
- 3) Make the data sending/receiving map
- 4) Parameter setting in KGLWIN High Speed Link parameter setting item
- 5) Execute program and parameter download from the online menu
- 6) Change the mode to RUN from the online menu.
- 7) Check the High Speed Link status through flag monitor
- 8) If the error occurs, repeat the above from 1).

The High Speed Link parameter for the system of program example is set as follows.

K200S (station 0) High Speed Link parameter											
薯Parar	meter [New	v Project1]									۱×
Basic	Interru	ipt I/O	Link1	Link2							
Link:	Enable	Self Station No): 💽 💌	Base: 0	Ŧ	Slot: 0 💌 T	ype:	Rnet	-		
No	Station	Unit Type	Tx	Device		Rx Device		Size	Block	No	
Q	1	Remote Out		P003		P000		1		Ū.	
1	2	Remote In		P000	P004			2		1	
Ľ <u>č</u>											
1 Å											
5											
6											
171											النے ا

K2005 (station 0) High St

(C) High Speed Link speed fixing method.

The system of Example 1) is a simple system that the communication module of station 3 sends/receives the data of 1word per each station. And the calculation method for communication speed is as follows.

Formula St = P_scanA + C_scan St = *High Speed Link* max. transmission time P_scanA = PLC A max. program scan time C_scan = max. communication scan time

As P_scanA is PLC scan time on the above, if assuming that it is 3ms each for the above program, (available to verify through online-information read-PLC information)

 $\label{eq:c_scan} \begin{array}{l} C_scan = n1 \; x \; 180 us \; + n2 \; x \; 828 us \; + \; 1,000 us \\ n1 : output \; station \; number \\ n2 : input \; station \; number \\ \hline C_scan = 1 \; x \; 180 \; + \; 1 \; x \; 828 \; + \; 1,000 = \; 2,008 us \\ & St = P_scanA(=3ms) \; + \; Cscan(2ms) = \; 5ms \end{array}$

Therefore, the sending/receiving period should be set as min. more than 5ms.